

Lecture 3  
**Probabilistic Reliability**  
with  
**Info-Gap Uncertainty**

**Yakov Ben-Haim**  
**Technion**  
**Israel Institute of Technology**



# Contents

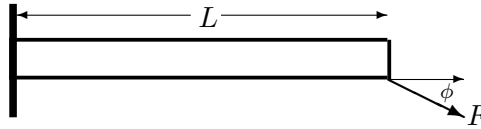
|          |   |           |
|----------|---|-----------|
| <b>1</b> | <b>Highlights (besancon2016lec03-001.tex)</b>                                     | <b>3</b>  |
| <b>2</b> | <b>Random Load on a Cantilever: Info-Gap Robustness Analysis (ps2p71-001.tex)</b> | <b>4</b>  |
| 2.1      | Problem Statement . . . . .   | 4         |
| 2.2      | Uniform-Bound Info-Gap Model . . . . .  | 4         |
| 2.3      | Fractional-Error Info-Gap Model . . . . .   | 5         |
| 2.4      | Probability of Failure . . . . .  | 6         |
| 2.5      | Hybrid Uncertainty: Probability with Info-Gaps . . . . .                          | 7         |
| <b>3</b> | <b>Random Events and Failure: Info-Gap Robustness Analysis (ps2p70-001.tex)</b>   | <b>8</b>  |
| 3.1      | Formulation . . . . .   | 8         |
| 3.2      | Probabilities of Failure . . . . .  | 8         |
| 3.3      | Uncertain Poisson Process . . . . .   | 9         |
| 3.4      | Robustness to Info-Gap Uncertainty in Poisson Process . . . . .                   | 9         |
| <b>4</b> | <b>Conclusion (besancon2016lec03-001.tex)</b>                                     | <b>11</b> |

# 1 Highlights

## § Info-Gap Robustness Analysis of:

- Random Loads on a Beam.
- Random Events and Failure.

## 2 Random Load on a Cantilever: Info-Gap Robustness Analysis



### 2.1 Problem Statement

- Rigid beam.
- $F$  = load at free end at angle  $\phi$ .
- $k$  = rotational stiffness at base.
- $\theta$  = angular rotation of beam:

$$\theta = \frac{F \sin \phi}{k} \quad (1)$$

- Design requirement:

$$|\theta| \leq \theta_c \quad (2)$$

- Problem: Load uncertain,  $F$ .

### 2.2 Uniform-Bound Info-Gap Model

#### § We know:

- $F$  is nominally zero.
- $F$  may deviate greatly from zero.

#### § We do not know:

- Maximum deviation from zero.
- Probability distribution of  $F$ .

#### § Info-gap model of uncertainty in $F$ :

$$\mathcal{U}(h) = \{F : |F| \leq h\}, \quad h \geq 0 \quad (3)$$

Two levels of uncertainty:

- $F$  unknown.
- Horizon of uncertainty,  $h$ , unknown.

#### § Derive the robustness by combining:

- System model: eq.(1).
- Performance requirement: eq.(2).
- Uncertainty model: eq.(3).

$$\hat{h}(\theta_c) = \max \left\{ h : \left( \max_{F \in \mathcal{U}(h)} |\theta| \right) \leq \theta_c \right\} \quad (4)$$

§ **Solution method.** Start from the inside:

Let  $m(h)$  denote the inner maximum in eq.(4) that occurs for  $F = \pm h$ :

$$m(h) = \left| \frac{h \sin \phi}{k} \right| \leq \theta_c \implies \boxed{\hat{h}(\theta_c) = \frac{k\theta_c}{\sin \phi}} \quad (5)$$

§ **Two properties** of all info-gap robustness functions,  $\hat{h}(\theta_c)$ :

- **Trade off:** Better performance (smaller  $\theta_c$ ) has worse robustness (lower  $\hat{h}$ ).
- **Zeroing:** Predicted performance (no rotation) has zero robustness.

§ **Inverse of robustness:**  $m(h)$  is the inverse function of  $\hat{h}(\theta_c)$ :

$$m(h) = \theta_c \text{ if and only if } \hat{h}(\theta_c) = h \quad (6)$$

Hence: plot of  $m(h)$  vs  $h$  is the same as plot of  $\theta_c$  vs  $\hat{h}(\theta_c)$ .

### 2.3 Fractional-Error Info-Gap Model

§ **Different information, different robustness.**

§ **We know:**

- $F$  nominally equals  $\tilde{F}$ , a known positive value.
- $F$  may deviate greatly from  $\tilde{F}$ .
- $k$  nominally equals  $\tilde{k}$ , a known positive value.
- $k$  may deviate greatly from  $\tilde{k}$ .
- $k$  is non-negative.

§ **We do not know:**

- Maximum fractional deviation of  $F$  from  $\tilde{F}$ , or of  $k$  from  $\tilde{k}$ .
- Probability distribution of  $F$  or of  $k$ .

§ **Info-gap model** of uncertainty in  $F$  and  $k$ :

$$\mathcal{U}(h) = \left\{ F, k : \left| \frac{F - \tilde{F}}{\tilde{F}} \right| \leq h, k > 0, \left| \frac{k - \tilde{k}}{\tilde{k}} \right| \leq h \right\}, \quad h \geq 0 \quad (7)$$

§ **Derive the robustness** by combining:

- System model: eq.(1), p.4:  $\theta = (F \sin \phi)/k$ .
- Performance requirement: eq.(2), p.4:  $|\theta| \leq \theta_c$ .
- Uncertainty model: eq.(7).

$$\hat{h}(\theta_c) = \max \left\{ h : \left( \max_{F, k \in \mathcal{U}(h)} |\theta| \right) \leq \theta_c \right\} \quad (8)$$

§ **Solution method:** start with the inner maximum of eq.(8).

The inner maximum,  $m(h)$ , occurs at:

$$F = (1 + h)\tilde{F}, \quad k = \max[0, (1 - h)\tilde{k}] \quad (9)$$

Thus, for  $h < 1$ :

$$m(h) = \frac{(1+h)\tilde{F} \sin \phi}{(1-h)\tilde{k}} \leq \theta_c \implies (1+h)\tilde{F} \sin \phi \leq (1-h)\tilde{k}\theta_c \implies \hat{h} = \frac{\tilde{k}\theta_c - \tilde{F} \sin \phi}{\tilde{k}\theta_c + \tilde{F} \sin \phi} \quad (10)$$

or zero if this is negative. Note that  $\hat{h}$  is less than 1.

§ **Two properties:**

- Trade off: greater robustness only at greater allowed deflection.
- Zero robustness at estimated deflection.

§ **Meaning of numerical values of  $\hat{h}$ :**

- $\hat{h} = 0.2$  implies performance guaranteed up to 20% error in both  $\tilde{F}$  and  $\tilde{k}$ .
- $\hat{h} = 0.7$  implies performance guaranteed up to 70% error in both  $\tilde{F}$  and  $\tilde{k}$ .
- Asymptotic robustness:

$$\lim_{\theta_c \rightarrow \infty} \hat{h}(\theta_c) = 1 \quad (11)$$

- Max possible robustness (in this problem:) immunity to 100% error.
  - Small? Large? Large enough?
  - Important and difficult **value judgment**.

## 2.4 Probability of Failure

§ Different prior knowledge:

- $k$  is known.
- $F$  is exponentially distributed random variable:

$$p(F) = \lambda e^{-\lambda F}, \quad F \geq 0 \quad (12)$$

§ **Failure of failure:**

- **Mechanical** failure [violating design requirement, eq.(2)]:

$$|\theta| > \theta_c \quad (13)$$

- **Probability** of failure:

$$P_f = \text{Prob}(|\theta| > \theta_c) \quad (14)$$

§ **Deriving probability of failure:**

$F$  is non-negative so  $\theta$  is also non-negative. Hence the probability of failure is:

$$P_f(\lambda) = \text{Prob}(|\theta| > \theta_c) = \text{Prob}(\theta > \theta_c) = \text{Prob}\left(\frac{F \sin \phi}{k} > \theta_c\right) = \text{Prob}\left(F > \frac{k\theta_c}{\sin \phi}\right) = \exp\left(-\frac{\lambda k\theta_c}{\sin \phi}\right) \quad (15)$$

## 2.5 Hybrid Uncertainty: Probability with Info-Gaps

§ Continue from section 2.4, but with  $\lambda$  **uncertain**.

§ **We know:**

- $\tilde{\lambda}$ , an estimate of  $\lambda$ .
- $\lambda$  is positive.

§ **We do not know:**

- Maximum fractional error of the estimate.
- Probability distribution of  $\lambda$ .

§ **Info-gap model** for uncertainty in  $\lambda$ :

$$\mathcal{U}(h) = \left\{ \lambda : \lambda > 0, \left| \frac{\lambda - \tilde{\lambda}}{\tilde{\lambda}} \right| \leq h \right\}, \quad h \geq 0 \quad (16)$$

§ **Two types of failure:**

- **Mechanical failure.** Rotation too large:

$$|\theta| > \theta_c \quad (17)$$

- **Probabilistic failure.** Probability of failure too large:

$$\text{Prob}(|\theta| > \theta_c) > P_c \quad (18)$$

§ **Evaluate robustness** with respect to probabilistic failure:

$$\hat{h} = \max \left\{ h : \left( \max_{\lambda \in \mathcal{U}(h)} P_f(\lambda) \right) \leq P_c \right\} \quad (19)$$

- Start with the inner maximum of eq.(19),  $m(h)$ .
- From eq.(15), p.6, the inner maximum occurs at  $\lambda = \max[0, (1-h)\tilde{\lambda}]$ :

$$m(h) = \exp \left( -\frac{(1-h)\tilde{\lambda}k\theta_c}{\sin \phi} \right) \leq P_c \implies \frac{(1-h)\tilde{\lambda}k\theta_c}{\sin \phi} \geq -\ln P_c \implies \boxed{\hat{h}(P_c) = 1 + \frac{\sin \phi}{\tilde{\lambda}k\theta_c} \ln P_c} \quad (20)$$

or zero if this is negative.

§ **Two properties:**

- **Trade off:**  $\hat{h}(P_c)$  decreases (gets worse) as  $P_c$  decreases (gets better).
- **Zeroing:** Robustness vanishes at nominal  $P_f$ :

$$\hat{h}(P_c) = 0 \quad \text{if} \quad P_c = P_f(\tilde{\lambda}) = \exp \left( -\frac{\tilde{\lambda}k\theta_c}{\sin \phi} \right) \quad (21)$$

### 3 Random Events and Failure: Info-Gap Robustness Analysis

#### 3.1 Formulation

##### § Problem Statement:

- **Adverse events occur** randomly, independently, with average rate  $\lambda$ /sec.
- **System fails** if  $n$  or more events occur within time  $T$ .

##### § Questions:

- What is probability of failure if  $n = 1$  or  $n = 2$ ?
- Suppose  $\lambda$  is uncertain. Evaluate robustness of failure probability.

#### 3.2 Probabilities of Failure

##### § Adverse events occur according to a **Poisson process**:

- Independent random events, constant average rate.
- Probability of exactly  $n$  events in duration  $T$  is:

$$P_n(T) = \frac{(\lambda T)^n}{n!} e^{-\lambda T}, \quad n = 0, 1, 2, \dots \quad (22)$$

##### § Failure probability for $n = 1$ :

- The probability of **no** events up to time  $T$  is  $P_0(T)$ .
- Thus, for  $n = 1$ , the probability of failure is  $1 - P_0(T)$ :

$$\boxed{P_{f,1} = 1 - e^{-\lambda T}} \quad (23)$$

##### § Failure probability for $n = 2$ :

- The probability of less than 2 events up to time  $T$  is  $P_0(T) + P_1(T)$ .
- Thus, for  $n = 2$ , the probability of failure is  $1 - P_0(T) - P_1(T)$ :

$$\boxed{P_{f,2} = 1 - e^{-\lambda T} - \lambda T e^{-\lambda T}} \quad (24)$$



### 3.3 Uncertain Poisson Process

§ **We know:**

- $\tilde{\lambda}$  = estimate of failure rate,  $\lambda$ .
- $s$  = estimate of error of  $\tilde{\lambda}$ .
- $\lambda$  is positive.

§ **We do not know:**

- True value of  $\lambda$ .
- Maximum fractional error of estimate.
- Probability distribution for  $\lambda$ .

§ **Info-gap model** for uncertainty in  $\lambda$ :

$$\mathcal{U}(h) = \left\{ \lambda : \lambda > 0, \left| \frac{\lambda - \tilde{\lambda}}{s} \right| \leq h \right\}, \quad h \geq 0 \quad (25)$$

§ **Two properties of all info-gap models:**

- **Contraction:**

$$\mathcal{U}(h) = \{ \tilde{\lambda} \} \quad (26)$$

- **Nesting:**

$$h < h' \implies \mathcal{U}(h) \subseteq \mathcal{U}(h') \quad (27)$$

### 3.4 Robustness to Info-Gap Uncertainty in Poisson Process

§ **System model:**  $P_{f,n}$  in eq.(23) or (24).

§ **Performance requirement.** Failure probability acceptably small:

$$P_{f,n} \leq P_c \quad (28)$$

§ **Uncertainty model:** eq.(25).

§ **Robustness function combines** system model, performance requirement, and uncertainty model.

§ **Evaluating the robustness** for  $n = 1$ .

- The robustness is defined as:

$$\hat{h}_1(P_c) = \max \left\{ h : \left( \max_{\lambda \in \mathcal{U}(h)} P_{f,1} \right) \leq P_c \right\} \quad (29)$$

- Let  $m_1(h)$  denote the inner maximum of eq.(29).
- According to eq.(23),  $m(h)$  occurs when  $\lambda$  is as large as possible:  $\lambda = \tilde{\lambda} + sh$ . Thus:

$$m_1(h) = 1 - e^{-(\tilde{\lambda}+sh)T} \leq P_c \implies \hat{h}_1(P_c) = \frac{-\tilde{\lambda}T - \ln(1 - P_c)}{sT} \quad (30)$$

or zero if this is negative.

- Note trade off and zeroing.

§ **Evaluating the inverse of the robustness** for  $n = 2$ .

- The robustness is defined as:

$$\hat{h}_2 = \max \left\{ h : \left( \max_{\lambda \in \mathcal{U}(h)} P_{f,2} \right) \leq P_c \right\} \quad (31)$$

- Let  $m_2(h)$  denote the inner maximum of eq.(31), which is the **inverse of the robustness**.
- From eq.(24), p.8, we find:

$$\frac{\partial P_{f,2}}{\partial \lambda} = \lambda T^2 e^{-\lambda T} > 0 \quad (32)$$

- Thus  $m_2(h)$  occurs when  $\lambda$  is as large as possible:  $\lambda = \tilde{\lambda} + sh$ .
- Thus, from eq.(24):

$$m_2(h) = 1 - e^{-(\tilde{\lambda}+sh)T} - (\tilde{\lambda} + sh)T e^{-(\tilde{\lambda}+sh)T} \quad (33)$$

- The robustness is the greatest  $h$  at which:

$$m_2(h) \leq P_c \quad (34)$$

- **Problem:** We can't solve eq.(34) for  $h$ .
- **Solution:** No need to.
  - $m_2(h)$  is the inverse of  $\hat{h}(P_c)$ .
  - Plot of  $h$  vs  $m_2(h)$  equivalent to plot of  $\hat{h}(P_c)$  vs  $P_c$ .

## **4** *Conclusion*

In Conclusion

§ Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

§

In Conclusion

§ Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

§ Info-gap uncertainty is unbounded.

§

In Conclusion

§ Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

§ Info-gap uncertainty is unbounded.

§ Optimism: our models get better all the time.

§

In Conclusion

§ Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

§ Info-gap uncertainty is unbounded.

§ Optimism: our models get better all the time.

§ Realism: our models are wrong now

(and we don't know where or how much).

§

## In Conclusion

### § Info-gap uncertainty:

innovation, discovery, ignorance, surprise.

### § Info-gap uncertainty is unbounded.

### § Optimism: our models get better all the time.

### § Realism: our models are wrong now

(and we don't know where or how much).

### § Responsible decision making:

- Specify your goals.
- Maximize your robustness to uncertainty.
- Study the trade offs.
- Exploit windfall opportunities.