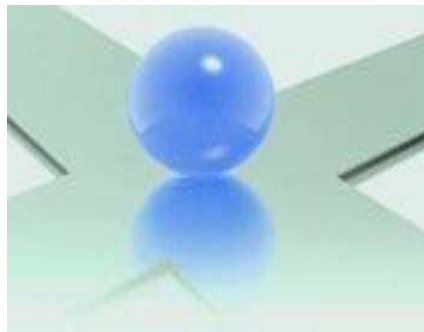


# Back to the Promised Land (Mathematical Analysis)

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# 1 *Highlights*

## § Binary decisions, expensive tests:

- **Airplane designs: Lockheed or Raytheon?**
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- Our **knowledge**?
- Our **knowledge** about our **knowledge**?
- Our **intuition** about our **ignorance**?
- Our ability to **use knowledge** and **manage ignorance**?

*Highlights*

§ **2 Systems, 1 Test: Probabilistic Alg.**

§ **Info-gap uncertainty on pdf: Robustify.**

§  **$n$  Systems,  $m$  Tests.**

§ **Source: <http://info-gap.com>**

## 2 *Two Systems, One Test*

---

<sup>0</sup>lectures\talks\lib\two-systems02.tex, 20.1.2016. See ‘Problem Set on Info-Gap Uncertainty’, \lectures\risk\homework\ps1rk.tex, #10. Yakov Ben-Haim, 2011, Two for the price of one: Info-gap robustness of the 1-test algorithm, ISIPTA2011, 25–28 July 2011, Innsbruck, Austria.

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- Choose one system.
- **Bigger is better.**

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- Flip a fair coin.
- 50/50 chance of success.

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- Enhanced chance of success?
- Which system to use?
- **It looks like 1 measurement can't help.**

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## § Theorem (Thomas Cover, 1987):<sup>1</sup>

If tested system chosen with probability 0.5,  
then  $P_s(q) > 0.5$ .

---

<sup>1</sup>Cover, Thomas M., 1987, Pick the largest number, chapter 5.1 in T. Cover and B. Gopinath, 1987, Open Problems in Communication and Computation, Springer-Verlag, Berlin.

### 3 *Two Systems, One Test, CDF Known*

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- **If  $F(x_r) < \frac{1}{2}$ , choose un-tested system.**
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§ **Theorem:**  $P_s = \frac{3}{4}$

**Proof:** Robert R. Snapp, 2005.<sup>2</sup>

---

<sup>2</sup>Robert R. Snapp, 2005, U of Vermont, \papers\2-systems-1test\isipta2011\covers-problem.pdf

## 4 *Robustness of Two Systems, One Test*

## § Recall no-knowledge algorithm:

- $q(y)$  is **any** pdf:  $q(y) > 0$  for all  $y \in \mathfrak{R}$ .
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Can we beat  $P_s(q) > 0.5$ ?

## § If we **know** $p(x_i)$ then $P_s = 0.75$ .

Can we achieve  $P_s(q) = 0.75$  w/o knowing  $p(x_i)$ ?

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- $\tilde{p}(x)$  highly **uncertain**.
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  - **Satisfy**  $P_s \geq P_c$ .
  - **Maximize robustness** to uncertain  $\tilde{p}$ .

§ **Info-gap model** for uncertain  $\tilde{p}(x)$ :  $\mathcal{U}(h)$ .

- **Nesting:**  $h < h' \implies \mathcal{U}(h) \subseteq \mathcal{U}(h')$ .





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- **Nesting:**  $h < h' \implies \mathcal{U}(h) \subseteq \mathcal{U}(h')$ .
- **Contraction:**  $\mathcal{U}(0) = \{\tilde{p}\}$ .
- $h$  is unbounded **horizon of uncertainty**.

§ **Robustness,  $\hat{h}(q, P_c)$ :**

**Maximum tolerable uncertainty.**

$$\hat{h}(q, P_c) = \max \left\{ h : \left( \min_{p \in \mathcal{U}(h)} P_s(q|p) \right) \geq P_c \right\}$$

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- **Prob of success:**  $P_s(q|\tilde{p}) > 0.5$
- **Putative optimal choice:**

$$\begin{aligned}\gamma^* &= \arg \max_{\gamma} P_s(q|\tilde{p}) \\ &= \tilde{\lambda}\sqrt{2}\end{aligned}$$

- **E.g.,  $\tilde{\lambda} = 1$ :**  $P_s(q|\tilde{p}) = 0.67 \gg 0.5$

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- **Robust to uncertainty in  $\tilde{p}(x)$ ???**



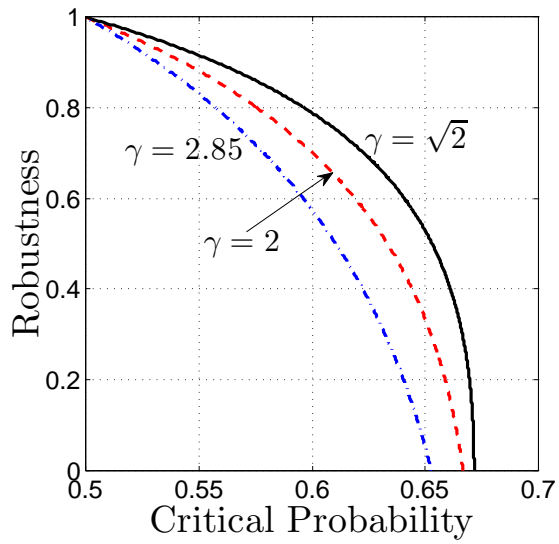


Figure 1: Robustness curves with  $\tilde{\lambda} = 1$ .

## § Zeroing:

Estimated prob of success: no robustness.

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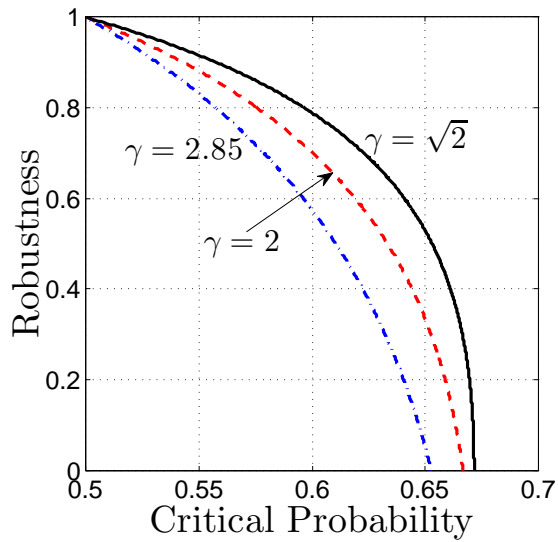
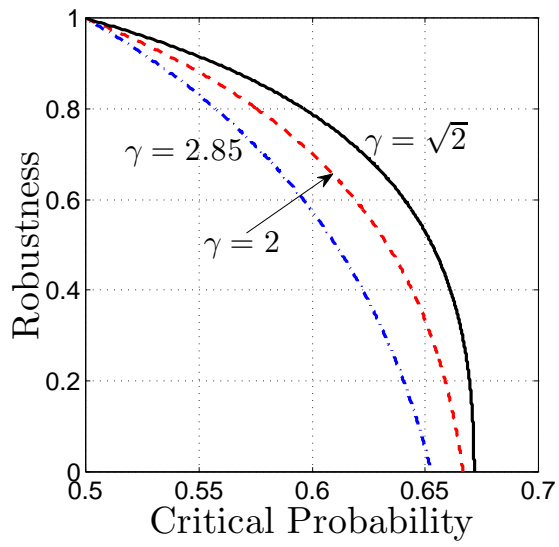
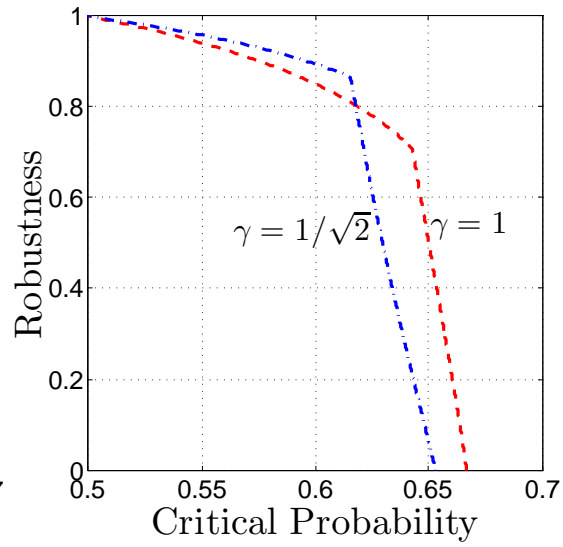


Figure 2: Robustness curves with  $\tilde{\lambda} = 1$ .

## § Zeroing:

Estimated prob of success: no robustness.

## § Trade off: robustness vs prob. of success.

Figure 3: Robustness curves with  $\tilde{\lambda} = 1$ .Figure 4: Robustness curves with  $\tilde{\lambda} = 1$ .

## § Preference reversal.

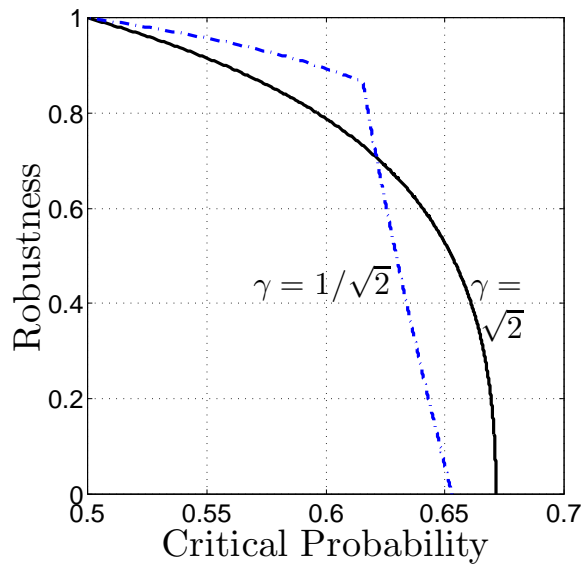


Figure 5: Robustness curves with  $\tilde{\lambda} = 1$ .

§ **Zeroing:** no robustness of estimate.

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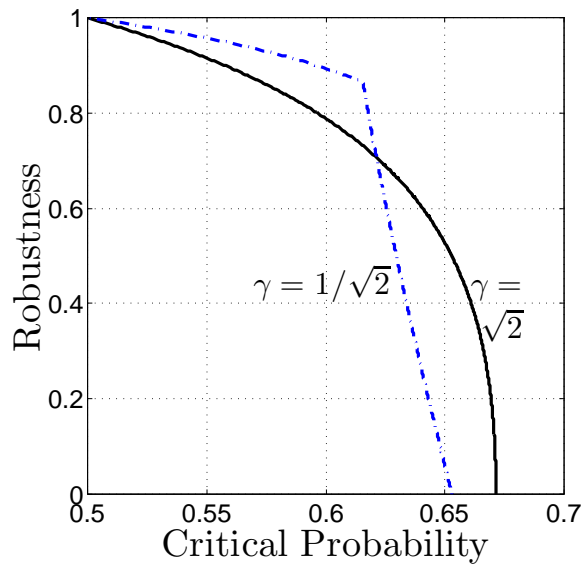


Figure 6: Robustness curves with  $\tilde{\lambda} = 1$ .

§ **Zeroing:** no robustness of estimate.

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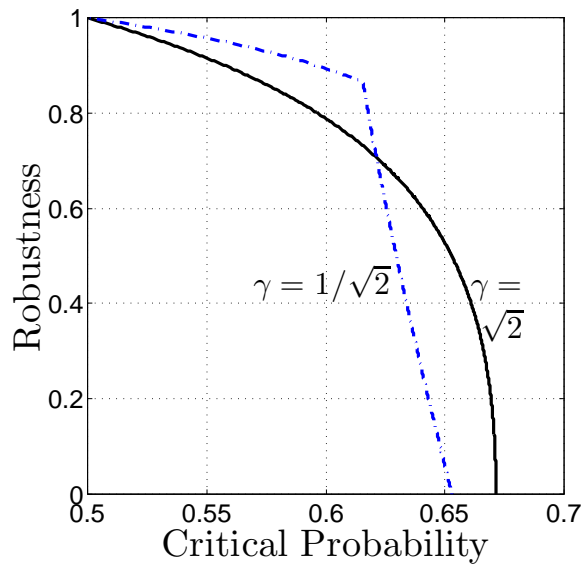


Figure 7: Robustness curves with  $\tilde{\lambda} = 1$ .

§ **Zeroing:** no robustness of estimate.

§ **Trade off:** robustness vs prob. of success.

§ **Preference reversal.**

- $\gamma = \sqrt{2}$  more robust for  $P_c > 0.62$ .
- $\gamma = 1/\sqrt{2}$  more robust for  $P_c < 0.62$ .

## **5** *Three Systems, Two Tests*

## § 3 Systems with qualities:

$$x_1 < x_2 < x_3$$

§



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§ Test two systems with revealed attributes:

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§ **Blind probability of success:**  $\frac{1}{3}$

## § Algorithm:

- $q(y)$  **any** non-zero pdf on  $\mathfrak{R}$ .
- Draw  $y$  from  $q(q)$ .
- If  $y < r_1$  choose **2** tested systems.
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## § Theorem:

If tested systems chosen with equal prob.

then  $P_s(q) > \frac{1}{3}$ .

## **6** *Three Systems, One Test*

## § 3 Systems with qualities:

$$x_1 < x_2 < x_3$$

§

§ 3 Systems with qualities:

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§ Test one system with revealed attribute  $r$ .

§



§ **3 Systems** with qualities:

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§ **Goal:** Select best system.

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## 7 *n* Systems, *m* Tests

§ Hypothesized generalization to *n* systems, *m* tests.

## 8 *Extensions*

§ Multiple attributes.

§ Adaptive testing.

§ Best possible probability of success.

## 9 *Final Thoughts*

§ We began by asking the following questions.

How good is:

- Our knowledge?
- Our knowledge about our knowledge?
- Our intuition about our ignorance?
- Our ability to use knowledge and manage ignorance?

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§ We began by asking the following questions.

How good is:

- Our knowledge?
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§ The 2-system 1-test example showed that:

- We are sometimes wrong about the answers.
- We should be ready for surprises.

## § A final thought on Optimism:

- **Scientific optimism:** We're approaching the truth.
-

## § A final thought on Optimism:

- **Scientific optimism:** We're approaching the truth.
- **My optimism:**
  - We will always be **surprised**.
  - **Science** will always continue.
  - **Uncertainty** will never disappear.